



Energy balance approach for oscillator parameter ID

Brian Mann

Asst. Professor

Mechanical Engineering and Materials Science

Duke University

2010 Inverse Problems Symposium

East Lansing, MI

June 6-8, 2010

Upload Code: 29-263



Outline

1. Background
2. Energy balance ID
3. Case studies
4. Summary

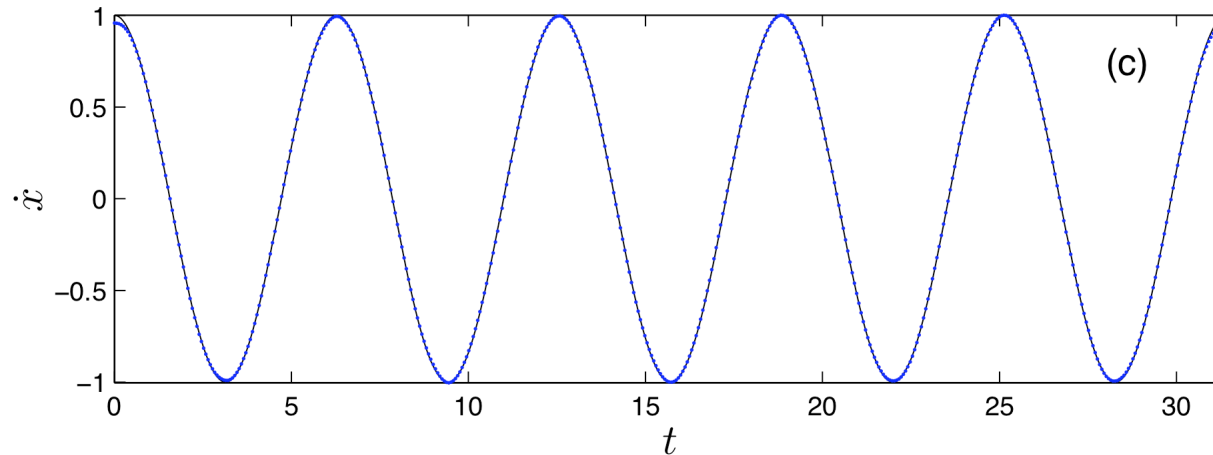
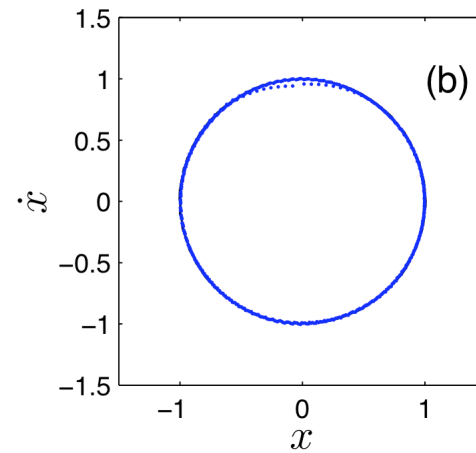
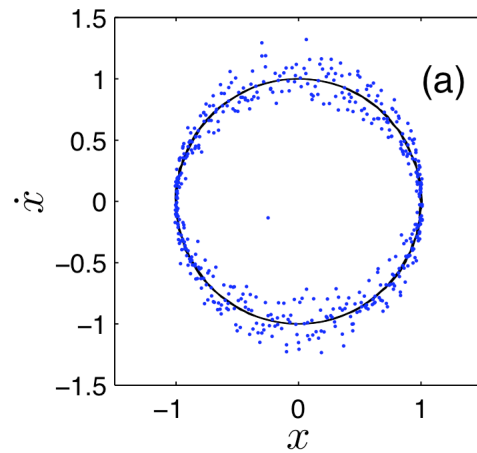


Select prior work

- 1992 - Mohammad, Worden, Tomlinson, Direct approach
- 1988 - Yashuda, Harmonic balance ID
- 1992 - Yiang and Feeny, ID from Chaotic response
- 2003 - Nichols and Virgin, ID from Chaotic interrogation
- 2006 - Liang and Feeny, Energy balance (friction)

Noisy data: Splines or smoothing splines

$$x(t) = b_{k0} + b_{k1}(t - t_k) + b_{k2}(t - t_k)^2 + b_{k3}(t - t_k)^3$$





Outline

1. Background
2. Energy balance ID approach
3. Case studies
4. Summary



Example energy balance: Oscillator

Example system

$$m\ddot{x} + c\dot{x} + kx + k_3x^3 = F \cos \Omega t$$

Balance energy

$$\int_{t_1}^{t_2} (m\ddot{x} + c\dot{x} + kx + k_3x^3) \dot{x} dt = \int_{t_1}^{t_2} \dot{x} F \cos \Omega t dt$$

Generic expression

$$T_{1 \rightarrow 2} + U_{1 \rightarrow 2} = W_{in} - W_d$$



Energy balance

Energy balance

$$T_{1 \rightarrow 2} + U_{1 \rightarrow 2} = W_{in} - W_d$$

Conservative terms

$$T_{1 \rightarrow 2} = \frac{1}{2} m (\dot{x}(t_2)^2 - \dot{x}(t_1)^2)$$

$$U_{1 \rightarrow 2} = \frac{1}{2} k (x(t_2)^2 - x(t_1)^2) + \frac{1}{4} k_3 (x(t_2)^4 - x(t_1)^4)$$

Nonconservative terms

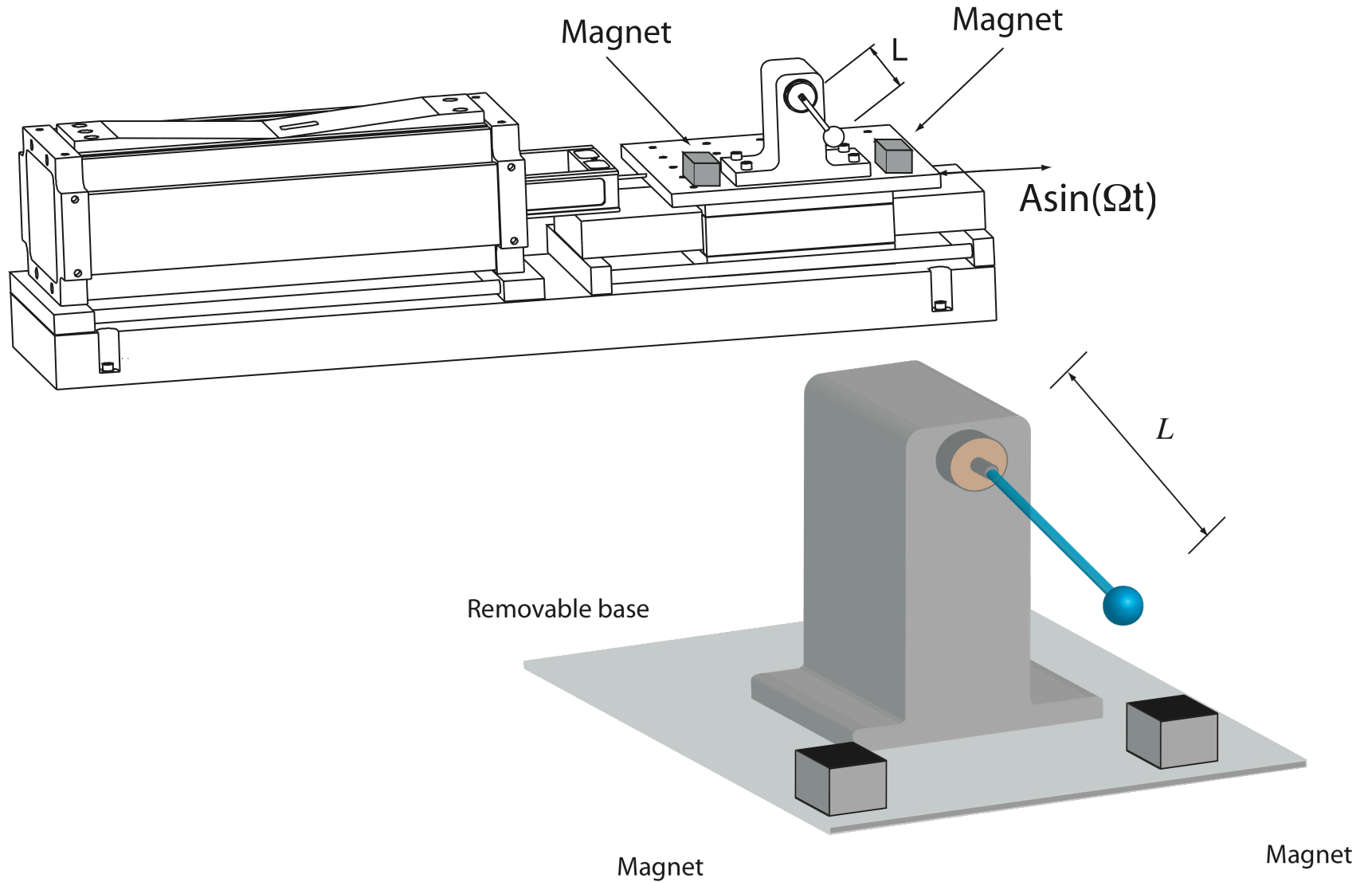
$$W_d = \int_{t_1}^{t_2} c \dot{x}^2 dt \quad W_{in} = \int_{t_1}^{t_2} \dot{x} F \cos \Omega t dt$$



Outline

1. Background
2. Energy balance ID approach
3. *Case studies*
4. Summary

Experimental system





Compare: Energy ID and analytical soln

Governing eqn

$$\ddot{\theta} + 2\mu\omega\dot{\theta} + \omega^2 \sin \theta$$
$$\ddot{\theta} + \omega^2 \theta = -f(\theta, \dot{\theta})$$

Assumed soln

$$\theta(t) = a \cos(\omega t + \phi) = a \cos \psi$$

Avg eqns

$$\dot{a} = \frac{1}{2\pi\omega} \int_0^{2\pi} \sin \psi f(a \cos \psi, -a\omega \sin \psi) d\psi = -\mu\omega a$$

$$\dot{\phi} = \frac{1}{2\pi\omega a} \int_0^{2\pi} \cos \psi f(a \cos \psi, -a\omega \sin \psi) d\psi = \frac{3a^2\beta}{8\omega}$$



Approx analytical solution

Integrated terms

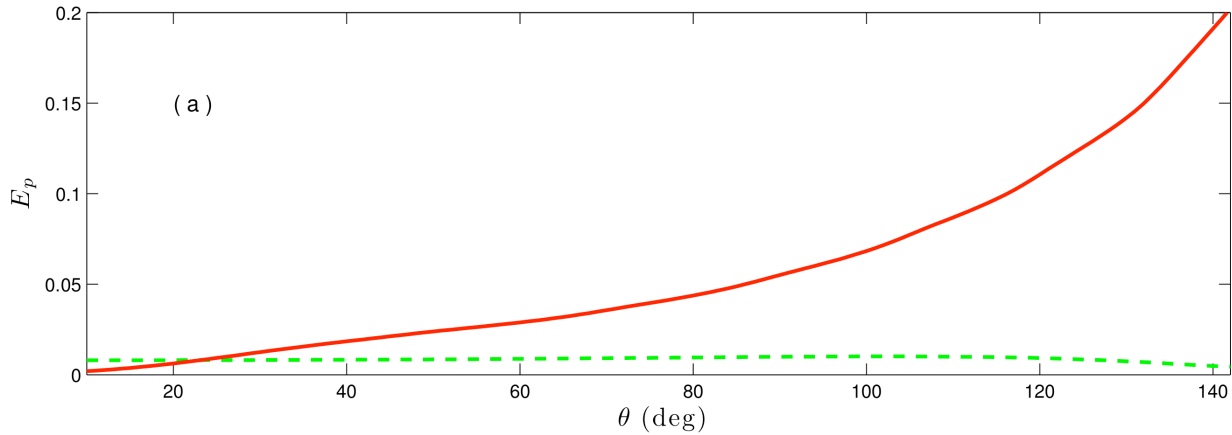
$$a = a_0 e^{-\mu\omega t}$$

$$\phi = \frac{a_0^2}{32\zeta} (e^{-2\mu\omega t} - 1) + \phi_0$$

Analytical soln

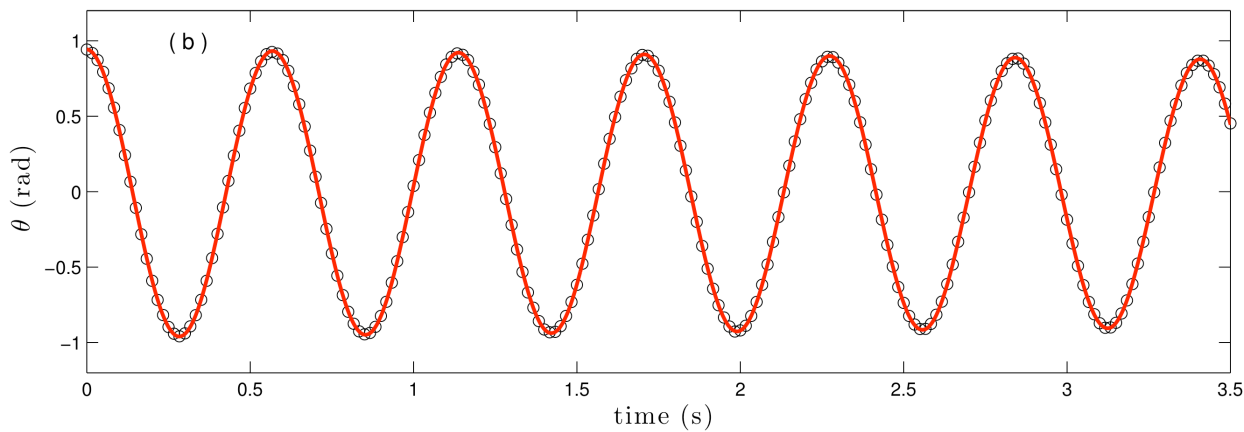
$$\theta(t) = \vartheta_0 e^{-\mu\omega t} \cos \left(\omega t + \frac{\vartheta_0^2}{32\mu} (e^{-2\mu\omega t} - 1) \right)$$

Comparison: Analytical vs energy



Error norm

$$E_p = \sqrt{\frac{1}{n_p} \left(\left(\frac{\mu_e - \mu}{\mu} \right)^2 + \left(\frac{\omega_e - \omega}{\omega} \right)^2 \right)}$$



Fit analytical soln

$$E_T = \sum_{k=1}^N (\theta_m(t_k) - \theta(t_k))^2$$

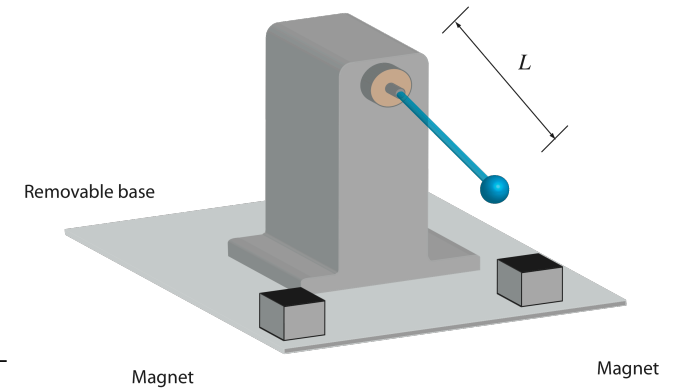
Magnetic pendulum example

Governing eqn

$$\ddot{\theta} + 2\mu\omega\dot{\theta} + \omega^2 \sin \theta + \sum_{n=1}^3 \hat{\alpha}_n (n+1)\theta^n = 0$$

Error norm

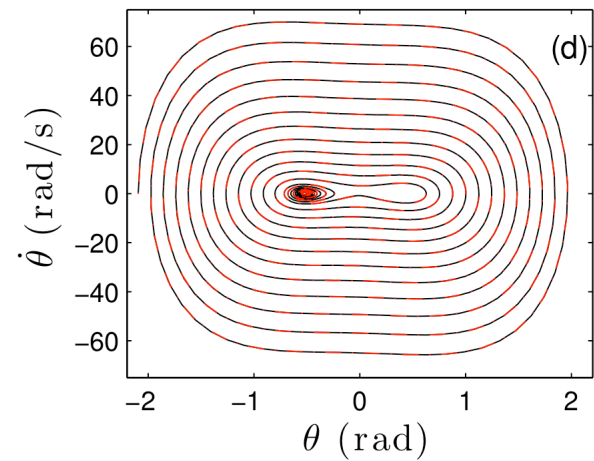
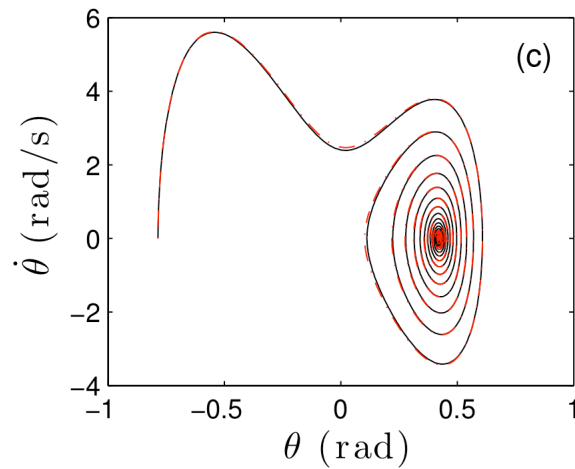
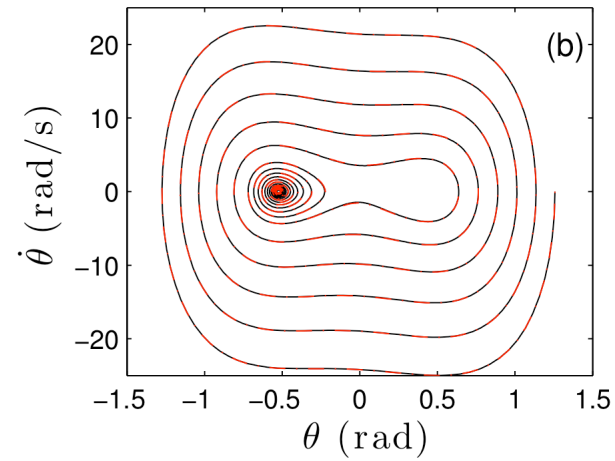
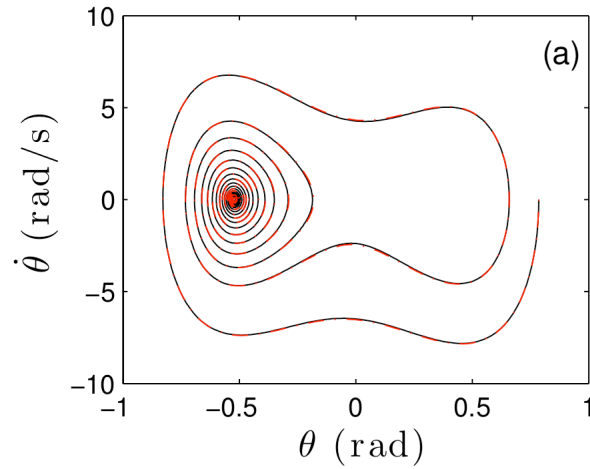
$$E_p = \sqrt{\frac{1}{n_p} \left(\left(\frac{\mu_e - \mu}{\mu} \right)^2 + \left(\frac{\omega_e - \omega}{\omega} \right)^2 + \sum_{n=1}^3 \left(\frac{\alpha_{ne} - \alpha_n}{\alpha_n} \right)^2 \right)}$$



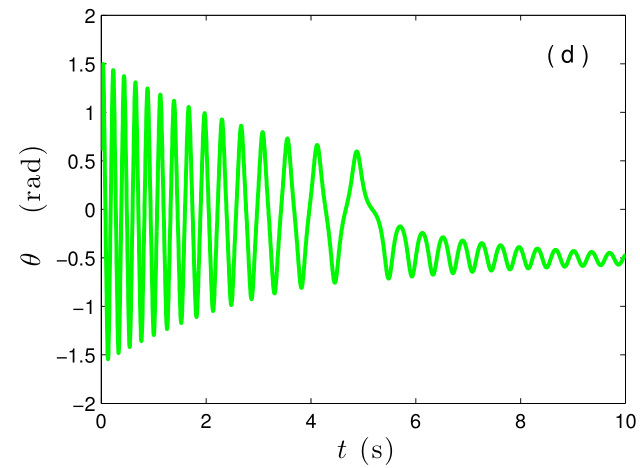
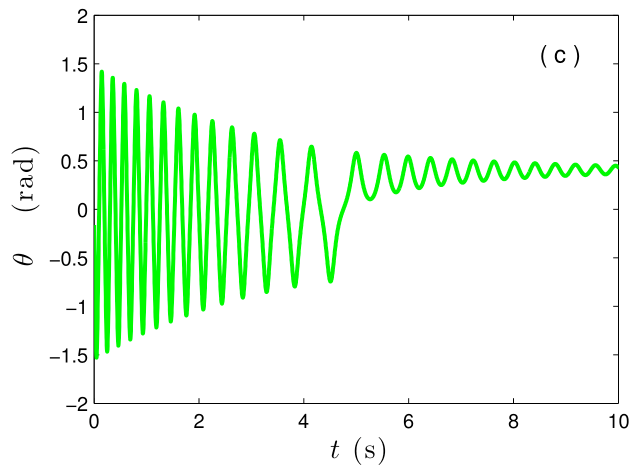
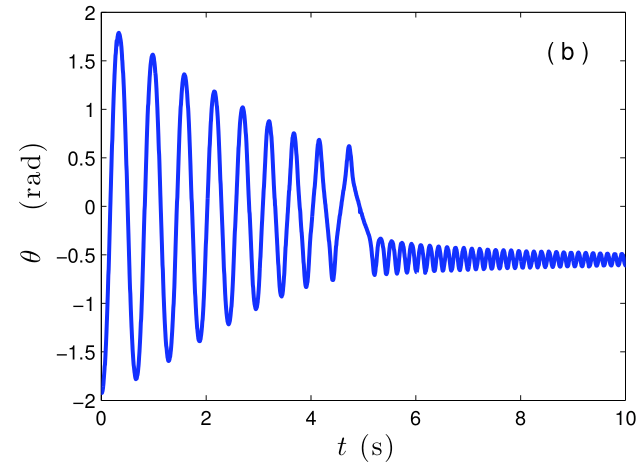
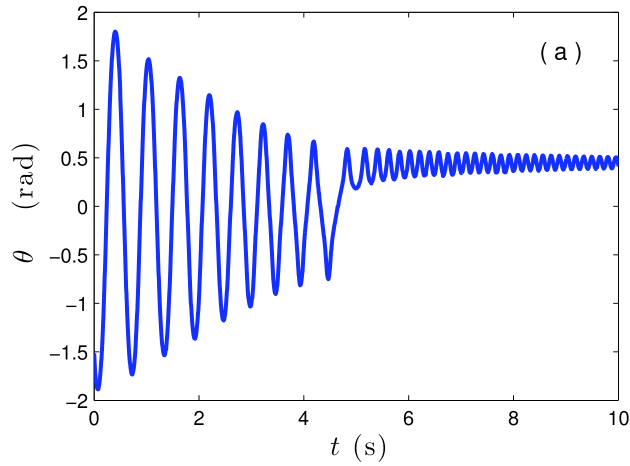
Steps

- Test energy balance on synthetic data
- Apply to experimental system

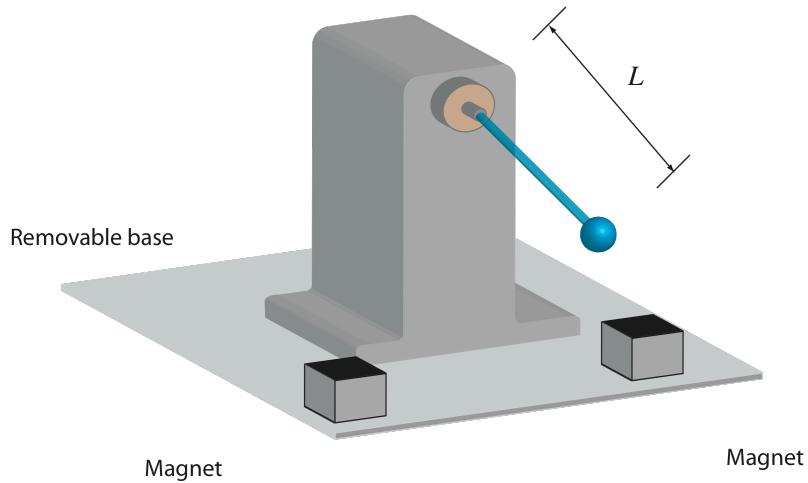
Comparisons for simulated data



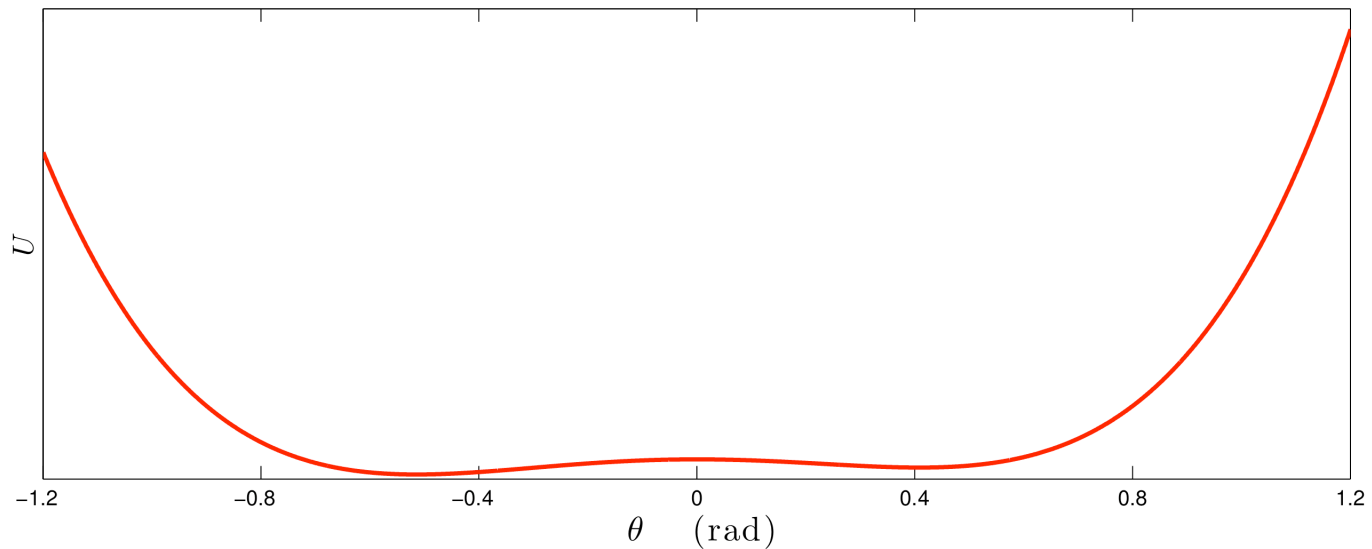
Experimental comparisons



Experimental bistable potential wells



Parameter	μ	ω (rad/s)	α_1 (N/rad)	α_2 (N/rad ²)	α_3 (N/rad ³)
Reference	0.0509	11.74	-138.3	21.3	163.1
Estimated	0.0510	11.71	-137.3	21.3	162.9
Experiment	0.0287	11.74	-145.25	25.74	188.11





Forced oscillator example

Example system

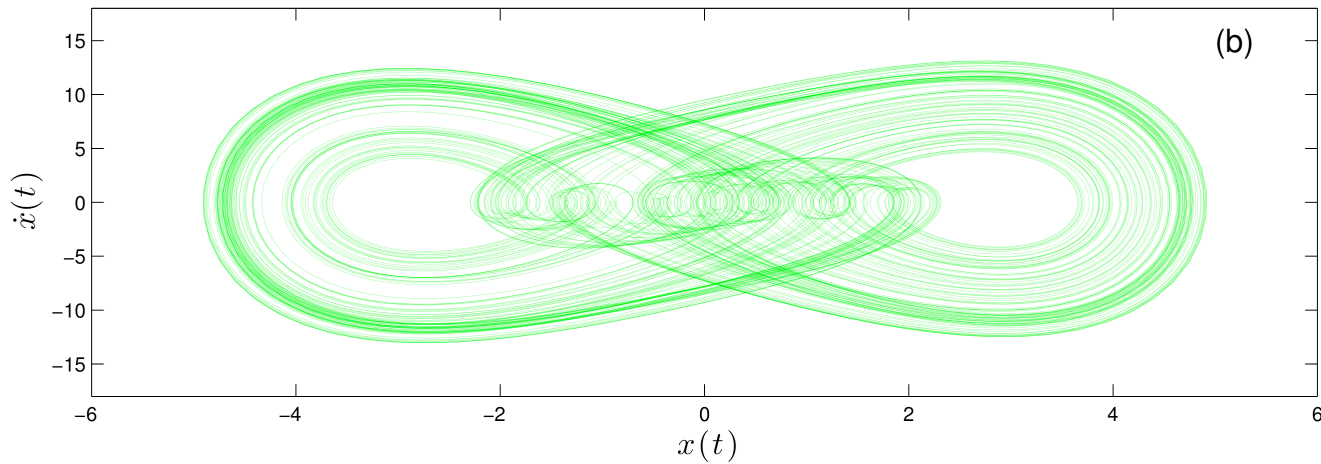
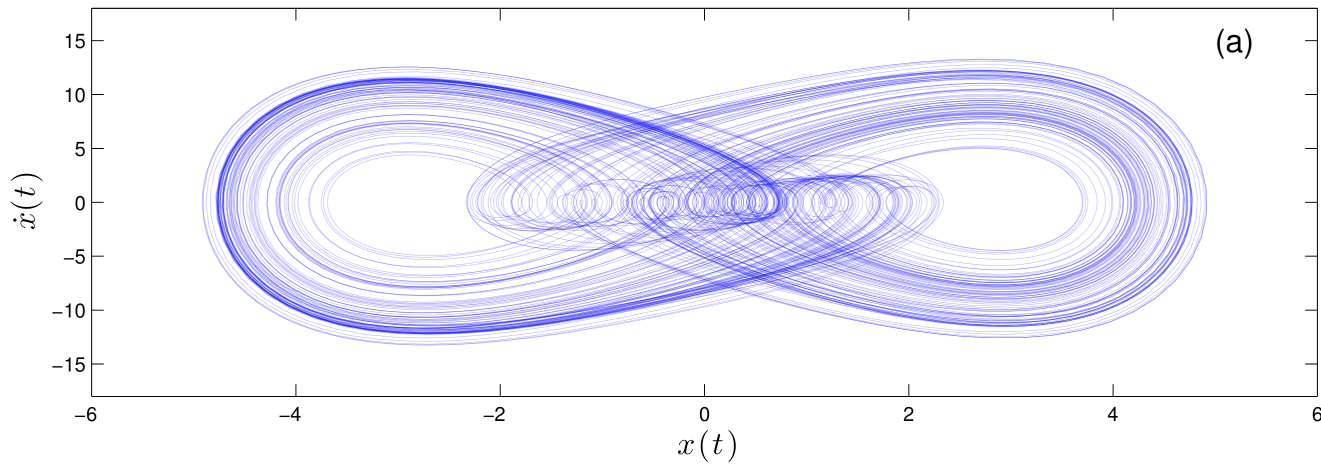
$$m\ddot{x} + c\dot{x} + kx + k_3x^3 = F \cos \Omega t$$

Work into system

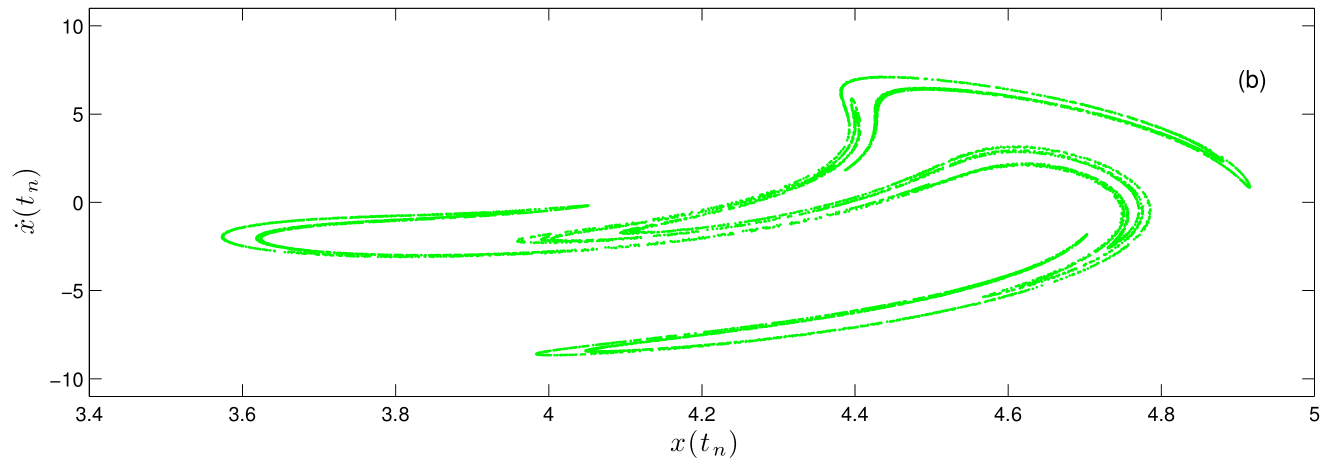
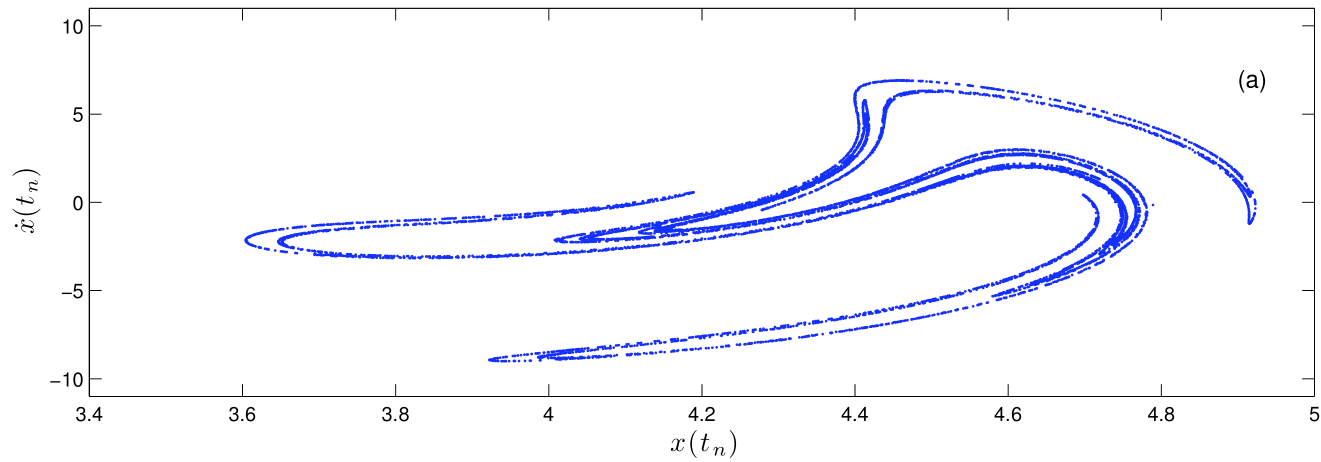
$$W_{in} = \int_{t_1}^{t_2} \dot{x} F \cos \Omega t dt$$

$$x(t) = b_{k0} + b_{k1}(t - t_k) + b_{k2}(t - t_k)^2 + b_{k3}(t - t_k)^3$$

Comparison of phase plane trajectories



Comparison of Poincare Sections



Acknowledgements

Collaborators:

Neil Sims, Firas Khasawneh

Research support:

- National Science Foundation
- Office of Naval Research Young Investigator Award
- ONR Program Manager Ronald Joslin

Disclaimer: The results and opinions expressed by the PI are not necessarily those of the funding agency.





Questions ?
